Local transformations of units in scalar–tensor cosmology

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Abstract
The physical equivalence of Einstein and Jordan frames in scalar–tensor
theories was explained by Dicke in 1962: they are related by a local
transformation of units. We discuss this point in a cosmological framework.
Our main result is the construction of a formalism in which all the physical
observables are frame-invariant. The application of this approach to CMB
codes is at present under analysis.

PACS numbers: 04.20.Cv, 98.80.Cq

1. Introduction

Scalar–tensor theories (ST) can be considered as the simplest extension of general relativity
(GR) that preserves a universal metric coupling between gravity and matter [1–3]. In such
theories the gravitational interaction is described in terms of both a metric tensor and a scalar
field. This feature, together with the relevance of scalar fields in cosmology, makes ST theories
cosmologically interesting [4–9].

ST theories can be formulated in different frames. In the so-called Jordan frame, the
Einstein–Hilbert action of GR is modified by the introduction of a scalar field φ with a non-
canonical kinetic term and a potential. This field replaces the Planck mass, which becomes a
dynamical quantity. On the other hand, the matter part of the action is just the standard one.

By Weyl-rescaling the Jordan metric $\tilde{g}_{\mu\nu}$ as in the following

$$\tilde{g}_{\mu\nu} = e^{-2b(\varphi)} g_{\mu\nu}, \tag{1}$$

one can express the ST action in the so-called Einstein frame. In the new variable $g_{\mu\nu}$,
the gravitational action is just the Einstein–Hilbert one plus a scalar field with canonically
normalized kinetic terms and an effective potential. On the other hand, in the matter action the
scalar field appears, through the rescaling factor multiplying the metric tensor everywhere. As
a consequence, the matter energy–momentum tensor is not covariantly conserved, and particle

physics parameters, such as masses and dimensionful coupling constants, are spacetime dependent.

The physical equivalence between the two frames was clearly discussed by Dicke in 1962 [10]. He showed that the local Weyl rescaling of equation (1) amounts to a local transformation of units; as a result the physical equivalence between different frames is trivial. We develop here a formalism that makes transparent such an equivalence: in our language all the observable quantities are manifestly frame-invariant (invariant under local transformations of units). Sections 1–4 are devoted to the construction of a frame-invariant action for ST theories. In sections 5 and 6 we discuss such a formalism in a cosmological framework.

2. Local transformations of units

We start summarizing Dicke's argument. Let us consider the separation $\bar{AB}$ between two spatial points A and B. The measure of $\bar{AB}$ in the units $\mathbf{u}$ is given by $l \equiv \bar{AB}/\mathbf{u}$. Under a transformation of units

$$\mathbf{u} \to \lambda^{-1/2}\mathbf{u} \tag{2}$$

the transformation properties of l are given by $l \to \lambda^{1/2}l$. The same argument we just applied to a spatial interval could have been applied to a time interval. Therefore, a spacetime interval $ds = \sqrt{g_{\mu\nu}\, dx^\mu\, dx^\nu}$ transforms under a transformation of units (2) in the following way $ds \to \lambda^{1/2}\, ds$. We should now remember that by definition the coordinates x^ρ are invariant under the transformation (2). As a result, the metric tensor transforms under the action of (2) like

$$g_{\mu\nu} \to \lambda g_{\mu\nu}. \tag{3}$$

Comparing now the last expression with equation (1), we can conclude that the local Weyl rescaling (1) has the meaning of a local transformation of units with $\lambda(x^\rho) = e^{-2b(\varphi(x^\rho))}$. With similar arguments one could derive the transformation properties of all the important quantities. For example one has

$$l \to e^{-b(\varphi)}l, \qquad m \to e^{b(\varphi)}m, \qquad \phi \to e^{b(\varphi)}\phi, \qquad \psi \to e^{\frac{3}{2}b(\varphi)}\psi,$$
$$A_\mu \to A_\mu, \qquad P_\mu \to P_\mu, \qquad \Gamma \to e^{b(\varphi)}\Gamma, \qquad \ldots \tag{4}$$

for a length, a mass, a scalar field, a spinor, a vector, the canonic momenta and a rate, respectively. It should be clear now that in the language of Dicke to choose a frame amounts to a local choice of units.

3. Frame-invariant variables

Knowing the transformation properties of the important quantities, one can define a set of frame-invariant variables through which to construct a frame-invariant action for ST theories. Let us start introducing a reference length l_R. Its transformation properties under local transformations of units are specified in equation (4). With this object we can construct, for example, the following frame-invariant quantities:

$$\bar{m} \equiv l_R m, \qquad \bar{\phi} \equiv l_R \phi, \qquad \bar{\psi} \equiv l_R^{3/2}\psi,$$
$$\bar{\Gamma} \equiv l_R \Gamma, \qquad h_{\mu\nu} \equiv l_R^{-2} g_{\mu\nu}, \qquad \ldots. \tag{5}$$

We will discuss in more detail the properties of the metric $h_{\mu\nu}$ when we will embed our discussion in a cosmological framework. We want to stress here that l_R is not a new scale of the theory and it is not a dynamical field. From a mathematical point of view, it is just a

quantity transforming like a length under a local transformation of units that we use for the definitions (5). Physically, its meaning becomes clear if one observes that only ratio between physical scales is really accessible to the experiments: l_R, therefore, represents a convenient reference magnitude appearing in such a ratio at the moment of performing a measurement. As a result, the choice of its value is dictated by practical convenience. For instance, in astrophysics l_R can be a reference atomic wavelength, in particle physics the inverse of some particle mass, or, in gravitational theories, the Planck length. ST theories are characterized by the possibility of using spacetime-dependent reference lengths. As we will see in the next section, in our language to choose a frame amounts to a choice of the function $l_R(x^\rho)$.

4. Frame-invariant action

Scalar–tensor theories can be defined in terms of frame-independent quantities by the action

$$S = S_G[h_{\mu\nu}, \varphi] + S_M[h_{\mu\nu} \, e^{-2b(\varphi)}, \bar{\phi}, \bar{\psi}, \ldots], \tag{6}$$

where the frame-independent fields $\bar{\phi}, \bar{\psi}, \ldots$, appearing in the matter action S_M are given by the combinations in equation (5). The gravity action is given by

$$S_G = \kappa \int d^4x \sqrt{-h}[R(h) - 2h^{\mu\nu}\partial_\mu\varphi\partial_\nu\varphi - 4U(\varphi)]. \tag{7}$$

In our language, choosing a frame corresponds to fixing the function $l_R(x^\rho)$ appropriately. The first possible choice is to take a constant $l_R(x^\rho) = l_{Pl}$, which corresponds to the Einstein frame. The gravity action takes the usual Einstein–Hilbert form

$$S_G = \kappa l_{Pl}^{-2} \int d^4x \sqrt{-g}[R(g) - 2g^{\mu\nu}\partial_\mu\varphi\partial_\nu\varphi - 4V(\varphi)], \tag{8}$$

with $V = l_{Pl}^{-2}U$. The combination in front of the integral fixes the Einstein-frame Planck mass, $\kappa l_{Pl}^{-2} = M_*^2/2 = (16\pi G_*)^{-2}$. The matter action is obtained from that of quantum field theory by substituting the Minkowsky metric $\eta_{\mu\nu}$ with $g_{\mu\nu} \, e^{-2b(\varphi)}$. Since in this frame the matter energy–momentum tensor is not conserved, particle physics quantities, such as masses and wavelengths, are not constant.

The other choice corresponds to the Jordan frame, which is obtained if one chooses $l_R(x^\rho) = \tilde{l}_P(x^\rho) = l_{Pl} e^{-b(\varphi(x^\rho))}$, where l_{Pl} is the previously defined Planck length in the Einstein frame. With this choice the matter action takes the standard form of quantum field theory (with $\eta_{\mu\nu} \to g_{\mu\nu}$), whereas the gravity action is

$$S_G = \frac{M_*^2}{2} \int d^4x \sqrt{-\tilde{g}} \, e^{2b(\varphi)}[R(\tilde{g}) - 2\tilde{g}^{\mu\nu}\partial_\mu\varphi\partial_\nu\varphi(1 - 3\alpha^2) - 4\tilde{V}(\varphi)], \tag{9}$$

where $\tilde{V} = \tilde{l}_P^{-2}U$, $\tilde{g}_{\mu\nu}$ is defined in (1) and $\alpha \equiv \frac{db}{d\varphi}$. Note that, in this frame, the rôle of the Planck mass is played by the spacetime-dependent quantity $M_* e^{b(\varphi)}$. Since $b(\varphi)$ disappears from the matter action, the energy–momentum tensor is now covariantly conserved.

5. Background cosmology

Assuming a FRW structure for the metric $g_{\mu\nu}$ in equation (5) we can consistently write the frame-invariant metric $h_{\mu\nu}$ in the following way

$$dh^2 = -a^2(\tau)\langle l\rangle_R^{-2}(\tau)(d\tau^2 - \delta_{ij} \, dx^i \, dx^j), \tag{10}$$

where $dh^2 = h_{\mu\nu} \, dx^\mu \, dx^\nu$ and we took in to account that in a generic frame $l_R(x^\rho) = \langle l\rangle_R(\tau) + \delta l_R(x^\rho)$ can eventually be spacetime dependent. The quantity $\langle l\rangle_R(\tau)$ represents a spatial average on a time-slice for an observer in the CMB rest-frame.

The metric (10) implies the following redshift-scale factor relation:

$$1 + z(\tau) = \frac{a(\tau_0)}{a(\tau)} \frac{\bar{l}_{\text{at}}(\tau)}{\bar{l}_{\text{at}}(\tau_0)}. \tag{11}$$

Here we wrote $l_{\text{R}} = l_{\text{at}}$ to underline that in redshift measurement an atomic wavelength is typically used as a reference length. The standard relation between the redshift and the scale factor, i.e. $1 + z = a(\tau_0)/a(\tau)$ is recovered only in that frame in which the reference wavelength l_{at} is constant in time and space. In ST theories this is the case of the Jordan frame.

Background fluids motion is described in the frame invariant phase space (x^i, P_j). On this phase space one can define a frame-invariant distribution function $F(x^i, P_j, \tau)$ and consequently a frame-invariant energy–momentum tensor

$$\bar{T}_{\mu\nu} = l_{\text{R}}^4 g_s \int \frac{\mathrm{d}^3 P}{(2\pi)^3} (-g)^{-1/2} \frac{P_\mu P_\nu}{P^0} F(x^i, P_, \tau), \tag{12}$$

where $\mathrm{d}^3 P = \mathrm{d}P_1 \, \mathrm{d}P_2 \, \mathrm{d}P_3$ and g_s counts the spin degrees of freedom.

From the last expression, we can read the frame-invariant energy density $\bar{\rho} = -\bar{T}_0^0$ and pressure $\bar{p}\delta_j^i = -\bar{T}_j^i$. By variation of equation (6) it is now possible to derive the frame-invariant equations of motion in a consistent frame-invariant FRW background. The results are given in [12].

6. Cosmological perturbations

We extend here the formalism we developed so far to first-order in perturbation theory. Let us start including first-order perturbations of the metric (10):

$$\mathrm{d}h^2 = a^2(\tau)/\langle l \rangle_{\text{R}}^2 \left[-\left(1 + 2\Psi - 2\frac{\delta l_{\text{R}}}{l_{\text{R}}} \right) \mathrm{d}\tau^2 + \left(1 - 2\Phi - 2\frac{\delta l_{\text{R}}}{l_{\text{R}}} \right) \delta_{ij} \, \mathrm{d}x^i \, \mathrm{d}x^j \right]. \tag{13}$$

From equation (13) we can read the definitions of frame-invariant scale factor and potentials:

$$\bar{a} \equiv a/\bar{l}_{\text{R}}, \qquad \bar{\Psi} \equiv \Psi - \frac{\delta l_{\text{R}}}{l_{\text{R}}}, \qquad \bar{\phi} \equiv \Phi + \frac{\delta l_{\text{R}}}{l_{\text{R}}}. \tag{14}$$

The first-order equations of motions obtained by equations (6) and (13) are given in [12].

In the next section, we will apply the formalism we developed so far to the Boltzmann equation. This can be of interest in many fields of cosmology.

7. The Boltzmann equation

The evolution of the phase-space density of a particle ψ, $F_\psi\left(x_\psi^i, P_j^\psi, \tau\right)$ is given by the Boltzmann equation:

$$\frac{\partial F^\psi}{\partial \tau} + \frac{\mathrm{d}x_\psi^i}{\mathrm{d}\tau} \frac{\partial F^\psi}{\partial x_\psi^i} + \frac{\mathrm{d}P_j^\psi}{\mathrm{d}\tau} \frac{\partial F^\psi}{\partial P_j^\psi} = \left[\frac{\mathrm{d}F^\psi}{\mathrm{d}\tau} \right]_{\text{C}}. \tag{15}$$

The frame-invariance of the LHS is trivially checked. Working with our variables, it is an immediate consequence of the manifest frame-invariance of the geodesic equation [12]:

$$\frac{\mathrm{d}P_j^\psi}{\mathrm{d}\tau} - P_0^\psi \partial_j(\bar{\Psi} + \log \bar{m}) = 0. \tag{16}$$

The collisional term for a generic process $\psi + a + b + \cdots \leftrightarrow i + j + \cdots$ reads

$$
\begin{aligned}
\left[\frac{\mathrm{d}F_\psi}{\mathrm{d}\tau}\right]_C \left(x_\psi^i, P_j^\psi, \tau\right) = {} & \frac{1}{2P_0^\psi} \int \mathrm{d}\Pi^a\, \mathrm{d}\Pi^b \cdots \mathrm{d}\Pi^i\, \mathrm{d}\Pi^j \cdots \\
& \times (2\pi)^4 \delta^4 (P^\psi + P^a + P^b \cdots - P^i - P^j \cdots) \\
& \times \left[|\mathcal{M}|^2_{\psi+a+b+\cdots\to i+j+\cdots} F_\psi F_a F_b \cdots (1 \pm F_i)(1 \pm F_j) \cdots \right. \\
& \left. - |\mathcal{M}|^2_{i+j+\cdots\to\psi+a+b+\cdots} F_i F_j \cdots (1 \pm F_\psi)(1 \pm F_a)(1 \pm F_b) \cdots \right],
\end{aligned}
\tag{17}
$$

where the '+' applies to bosons and the '−' to fermions, and $\mathrm{d}\Pi$ is the frame-invariant quantity

$$
\begin{aligned}
\mathrm{d}\Pi & \equiv l_\mathrm{R}^2 \frac{\mathrm{d}^4 P}{(2\pi)^3} (-g)^{-1/2} \delta(P^2 + m^2) \Theta(P^0) \\
& = l_\mathrm{R}^2 \frac{\mathrm{d}^3 P}{(2\pi)^3} \frac{(-g)^{-1/2}}{2P^0},
\end{aligned}
\tag{18}
$$

with $\mathrm{d}^4 P = \mathrm{d}P_0\, \mathrm{d}^3 P$. The delta-function in equation (17) depends on momenta with low indices.

8. Conclusions

Following Dicke's argument [10], we discussed here the relation between different frames in ST theories in terms of local transformations of units. In this language the physical equivalence of Einstein and Jordan frames is manifest and all the physical observables can be written in terms of frame-invariant quantities. We applied such a formalism to the first-order perturbed Boltzmann equation. Its frame-invariant expression (15) can be of interest in many analytical and numerical computations.

Acknowledgments

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